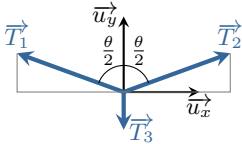


$$\vec{T}_1 \begin{pmatrix} -T_1 \sin \theta / 2 \\ T_1 \cos \theta / 2 \end{pmatrix}$$



$$\vec{T}_2 \begin{pmatrix} T_2 \sin \theta / 2 \\ T_2 \cos \theta / 2 \end{pmatrix}$$

$$\vec{T}_3 \begin{pmatrix} 0 \\ -T_3 \end{pmatrix}$$